Comparison of Computational Methods for the Estimation of the Dielectrophoretic Force Acting on Biological Cells and Aggregates in Silicon Lab-on-Chip Devices

Sarah Burgarella¹, Federica Maggioni², Giovanni Naldi²

¹ STMicroelectronics, Agrate Brianza, Milan, Italy
² Department of Mathematics, University of Milan, Italy





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• Dielectrophoresis (DEP) is a promising method for the automated separation of biological cells and aggregates based on the exploitation of their physical properties when subjected to non-uniform electric fields.

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INTRODUCTION

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 In this work we have studied, developed and compared different methods for the force computation depending on the field non-uniformity factor and on the dimensions of the cellular aggregate







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CELLULAR AGGREGATE'S MODEL





Geometrical model of the reciprocal single cells disposition inside the aggregate and a microscope image of a mouse Langerhans islet.

DEP FORCE IN TIME CONSTANT ELECTRIC FIELDS



$$\langle F_{\mathsf{DEP}} \rangle_i = \underbrace{2\pi\varepsilon_m R^3 F_{\mathsf{CM}}^{(1)} \left[\nabla \boldsymbol{E}_0^2 \right]_i}_{i}$$

Dipole approximation

where

$$F_{\rm CM}^{(1)} = rac{\varepsilon_{p} - \varepsilon_{m}}{\varepsilon_{p} + 2\varepsilon_{m}}$$

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$$F_{CM}^{(1)} = rac{arepsilon_{p} - arepsilon_{m}}{arepsilon_{p} + 2arepsilon_{m}}$$
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DEP FORCE IN ALTERNATED ELECTRIC FIELDS

• $\boldsymbol{E} = E_{x,0} \cos(\omega t + \varphi_x) \boldsymbol{e}_x + E_{y,0} \cos(\omega t + \varphi_y) \boldsymbol{e}_y + E_{z,0} \cos(\omega t + \varphi_z) \boldsymbol{e}_z =$ $\Re[\boldsymbol{E}_0 e^{j(\omega t + \varphi)}]$

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- $\varepsilon \rightsquigarrow \varepsilon^* = \varepsilon + \frac{\sigma}{j\omega} \implies F_{\mathsf{CM}} = \frac{\varepsilon^*_{\mathbf{m}} \varepsilon^*_{\mathbf{p}}}{\varepsilon^*_{\mathbf{m}} + 2\varepsilon^*_{\mathbf{p}}} \in \mathbb{C}$
- The DEP force approximation is:

Dipole:
$$\langle \mathbf{F}_{\mathsf{DEP},\mathsf{dip}} \rangle_i = 4\pi\varepsilon_m R^3 \Re \left(F_{\mathsf{CM}}^{(1)} \bar{E}_i \frac{\partial \bar{E}_i^*}{\partial x_i} + \bar{E}_j \frac{\partial \bar{E}_i^*}{\partial x_j} + \bar{E}_k \frac{\partial \bar{E}_i^*}{\partial x_k} \right)$$

Quadrupole (Einstein notation): $\langle F_{\text{DEP,dip}} \rangle_i = \frac{4}{3} \pi \varepsilon_m R^5 \Re \left(F_{\text{CM}}^{(2)} \frac{\partial \bar{E}_k}{\partial x_j} \frac{\partial^2 \bar{E}_i}{\partial x_j \partial x_k} \right)$

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where

• \bar{E}_i is the electric field component root mean square value: $\bar{E}_i = \frac{E_i}{\sqrt{2}}$

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Force comparison

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- \overline{E}_i is the electric field component root mean square value: $\overline{E}_i = \frac{E_i}{\sqrt{2}}$
- E_i^* is the complex conjugate value of E_i

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ELECTRIC FIELD COMPUTATION



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Boundary conditions for the electric potential



ELECTRIC FIELD COMPUTATION



Boundary conditions for the electric potential



Computed electric potential



SECOND ORDER DERIVATIVES COMPUTATION

In the quadrupole DEP force term the second order field derivatives appear.

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A subdomain weak form equation in COMSOL Multiphysics PDE modes has been added to the existing model exploiting the Green's first identity:

$$\int_{\Omega} \mathbf{v} \Delta \varphi = \int_{\Omega} \nabla \mathbf{v} \cdot \nabla \varphi + \int_{\partial \Omega} \mathbf{v} \frac{\partial \varphi}{\partial \mathbf{n}}$$

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- Ω is the domain:
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- substitute v with the E_x computed value.
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• divide the equation in the part acting on Ω and the one on its boundary, we get $E1 = \frac{\partial E_x}{\partial x}$ that can be easily differentiated.

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 The two approximations are computed for different values of the field non-uniformity (electrodes width between 50 and 150 μ m) and of the particle's radius $(5-50 \,\mu m)$.

50 μm wide electrodes





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DEP FORCE POINTWISE APPROXIMATIONS: DIPOLE VS QUADRUPOLE

150 μm wide electrodes





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• A threshold value is fixed so that, given a field non-uniformity, it is possible to define a radius value below which the dipole approximation is enough.



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When the quadrupole approximation is not accurate, further multipole terms should be considered in the force calculation. ↓ Higher order electric field derivatives are introduced. ↓ Numerical approximation problems increase. ↓ Another method is proposed to compute the DEP force: the discrete method.

DISCRETE METHOD FOR THE FORCE COMPUTATION

In continuum area:

 $m{F} = \int_{\Omega} dm{f}^{(d\Omega)}$ where $dm{f}^{(d\Omega)}$ is the "infinitesimal" force acting on the "infinitesimal" volume $d\Omega$.

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In discrete area:

 $F = \sum_{i=1}^{N} dF_i$ where dF_i is the force acting on the *i*-th volume, small but finite.

Force comparison

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DISCRETE METHOD

The force is computed in the centers of each *small volume*, enough small to use the dipole force approximation, and, then, all the contributions are summed up to give the total DEP force.

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50 μm wide electrodes





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- The two DEP force approximations are computed for different values of the field non-uniformity and of the particle radius.
- Defining an appropriate function d that estimates the difference between the two approximations and a threshold value, a plot similar to the previous one is obtained.



RESUMPTIVE PLOT



DRAG FORCE

The particles move inside a microfluidic medium and experience a drag force.

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The particles move inside a microfluidic medium and experience a drag force.

For the dimensions and velocities that appear in this kind of dielectrophoretic experiments it could be approximated as

$$F_{\rm drag} = -6\pi\eta R v$$

where

- η is the fluid viscosity;
- *R* is the particle's radius;
- v is the particle's velocity.

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- the definition of the discrete force;
- the comparison between different computational methods for the DEP force depending on the field non-uniformity factor and on the aggregate's dimension;
- the definition of threshold values that allow to choose which computational method to be used;
- the experimental-simulation comparison that is quite good once we consider a further friction force that postpones the simulated motion start.

Thanks for your attention!

Contacts:

federica.maggioni@hotmail.it sarah.burgarella@st.com