

COMSOL
CONFERENCE
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Multigrid Implementation in COMSOL Multiphysics - Comparison of Theory and Practice



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How can you easily destroy your modeling effort?

Choose an inadequate solver or a badly parameterized one!

How can you avoid this?

You need knowledge on numerical methods – at least confidence in implemented solver techniques.

How can you obtain this?

Let the results for accepted model problems convince you about properties of a particular solver. Here: **geometric MG**.

If you like this ...

„COMSOL solver tuning“ (May 2014, Berlin). More general, more solver.

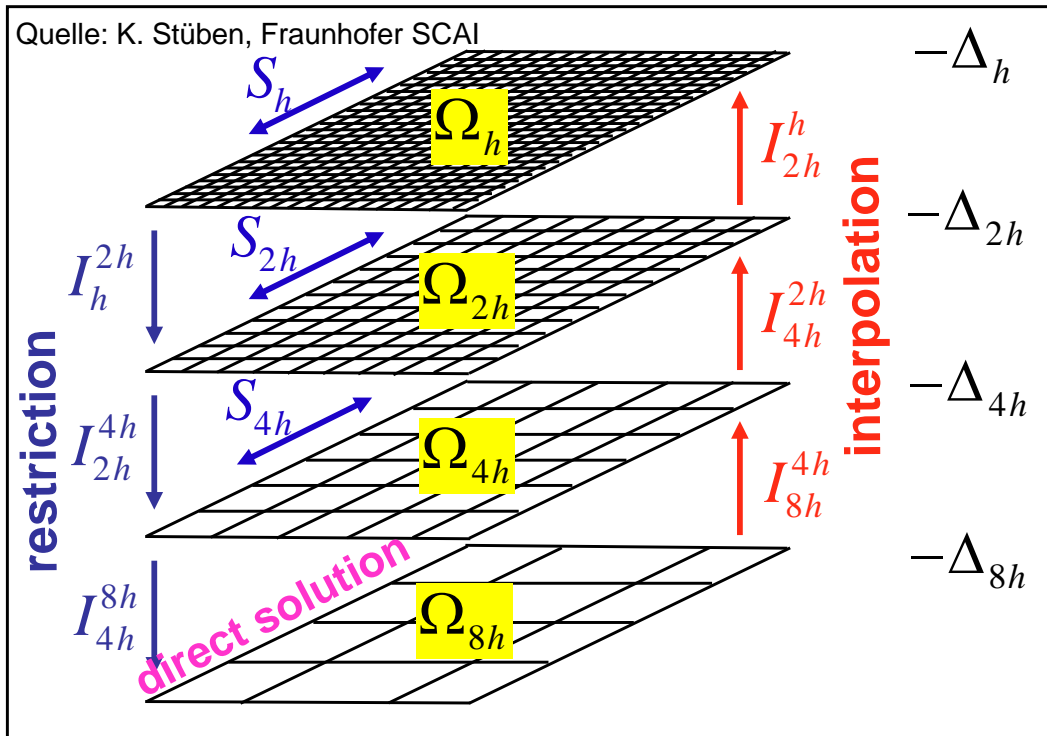


MG – a combination of **smoothing**

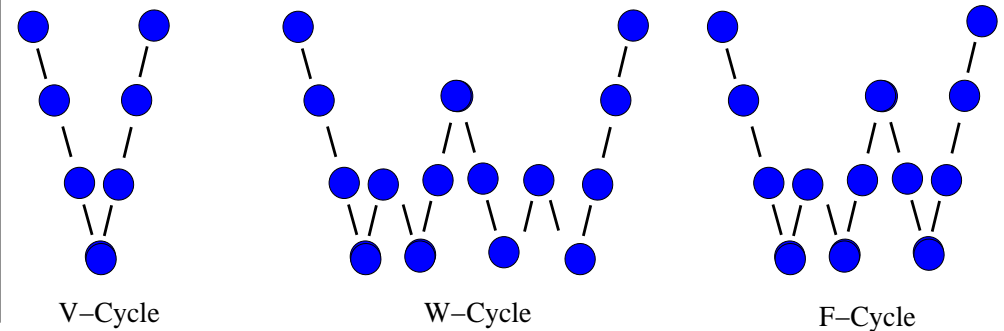
CGC

{	(1) <i>pre-smoothing</i>	$\bar{w}_h^{(n)} := RELAX^{\nu_1}(w_h^{(n-1)}, L_h, f_h)$		
	(2) <i>residual calculation</i>	$r_h^{(n)} := f_h - L_h \bar{w}_h^{(n)}$		
	(3) <i>residual restriction</i>	$r_H^{(n)} := I_h^H r_h^{(n)}$		
	(4) <i>exact solution of the coarse grid problem</i>	$L_H \tilde{e}_H^{(n)} = r_H^{(n)}$	step (4) recursively solved	⇒ multigrid
	(5) <i>correction transfer</i>	$\tilde{e}_h^{(n)} := I_H^h \tilde{e}_H^{(n)}$		
	(6) <i>correction</i>	$\tilde{w}_h^{(n)} := \bar{w}_h^{(n)} + \tilde{e}_h^{(n)}$		
	(7) <i>post-smoothing</i>	$w_h^{(n)} = RELAX^{\nu_2}(\tilde{w}_h^{(n)}, L_h, f_h)$		





multigrid cycling

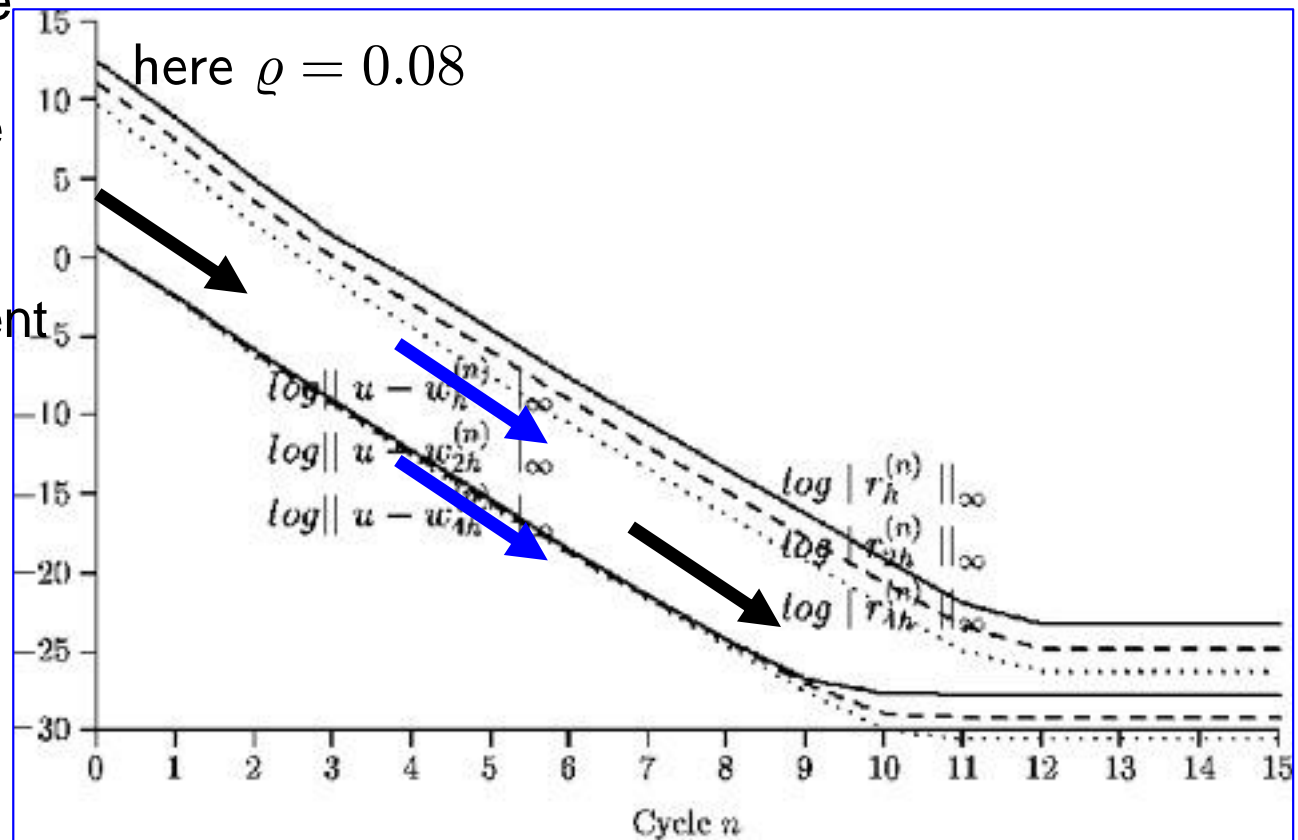


V-Cycle: cheap, fast
W-Cycle: robust, expensive, theory
F-Cycle: robust, cheaper than W



What would we like to have for a MG solver?

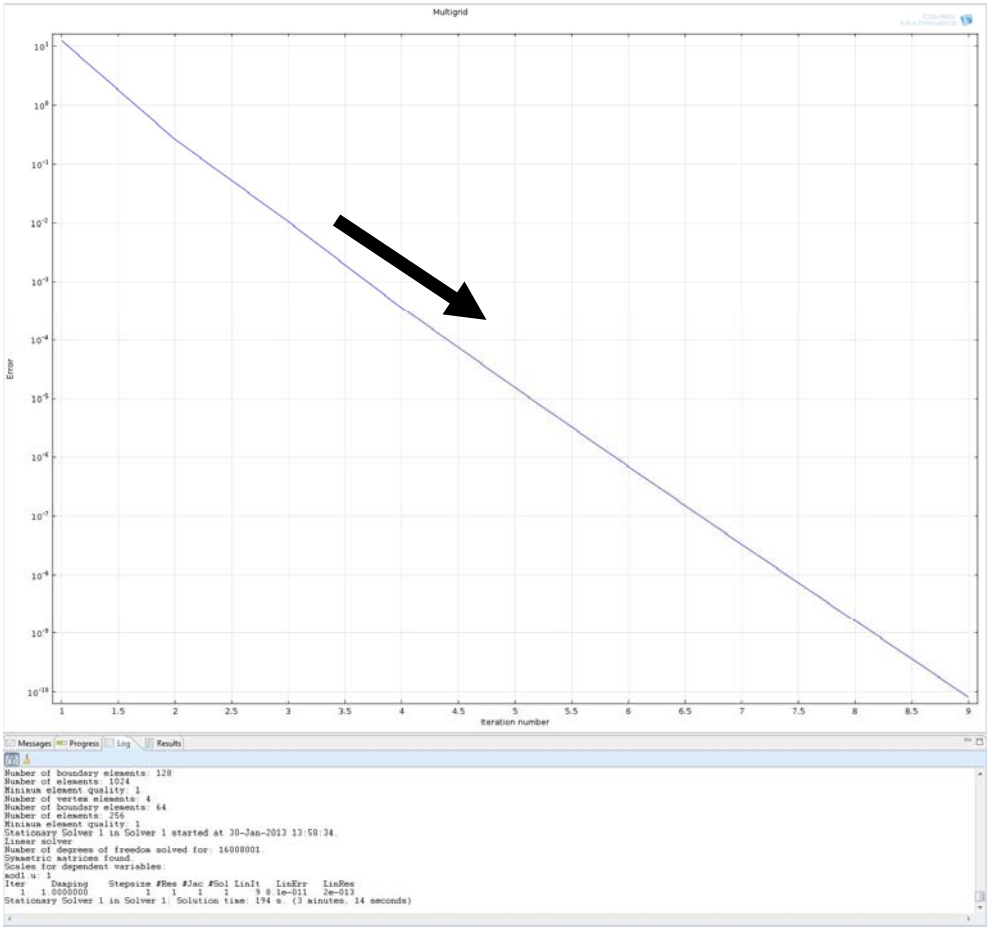
- steady convergence rate
(both error and residual reduction)
from the first cycle till the last one
- „h-independent“ convergence
- fast convergence
- convergence depends on the
quality of smoothing
- linear complexity $O(N)$
- moderate memory requirement
- faster than other solver



Poisson equation: $\varepsilon_x \frac{\partial^2 u}{\partial x^2} + \varepsilon_y \frac{\partial^2 u}{\partial y^2} = f(x, y)$ mit $\varepsilon_x = 1.0, \varepsilon_y = 1.0$
 „mapped mesh“: **16.008.001** d.o.f.

solver	smoother	time [s]	no. of cycles	time per cycle	Q_{comsol}	v. mem. (GB)
MG-V(2,1)-9L	SOR	175	10	2.8	0.046	17.0
MG-F(2,1)-9L	SOR	181	9	3.9	0.040	15.6
MG-W(2,1)-9L	SOR	184	9	4.3	0.040	15.7
MG-V(2,1)-9L	SSOR	195	10	3.7	0.053	15.9
MG-F(2,1)-9L	SSOR	197	9	5.6	0.048	15.0
MG-W(2,1)-9L	SSOR	203	9	6.3	0.048	15.0
MG-V(2,1)-9L	Vanka	196	10	4.8	0.053	18.0
MG-F(2,1)-9L	Vanka	205	9	6.1	0.048	18.0
MG-W(2,1)-9L	Vanka	210	9	6.9	0.048	18.0





Poisson equation: $\varepsilon_x \frac{\partial^2 u}{\partial x^2} + \varepsilon_y \frac{\partial^2 u}{\partial y^2} = f(x, y)$

„free triangular mesh“: **8.786.945 (8L), and 35.1**

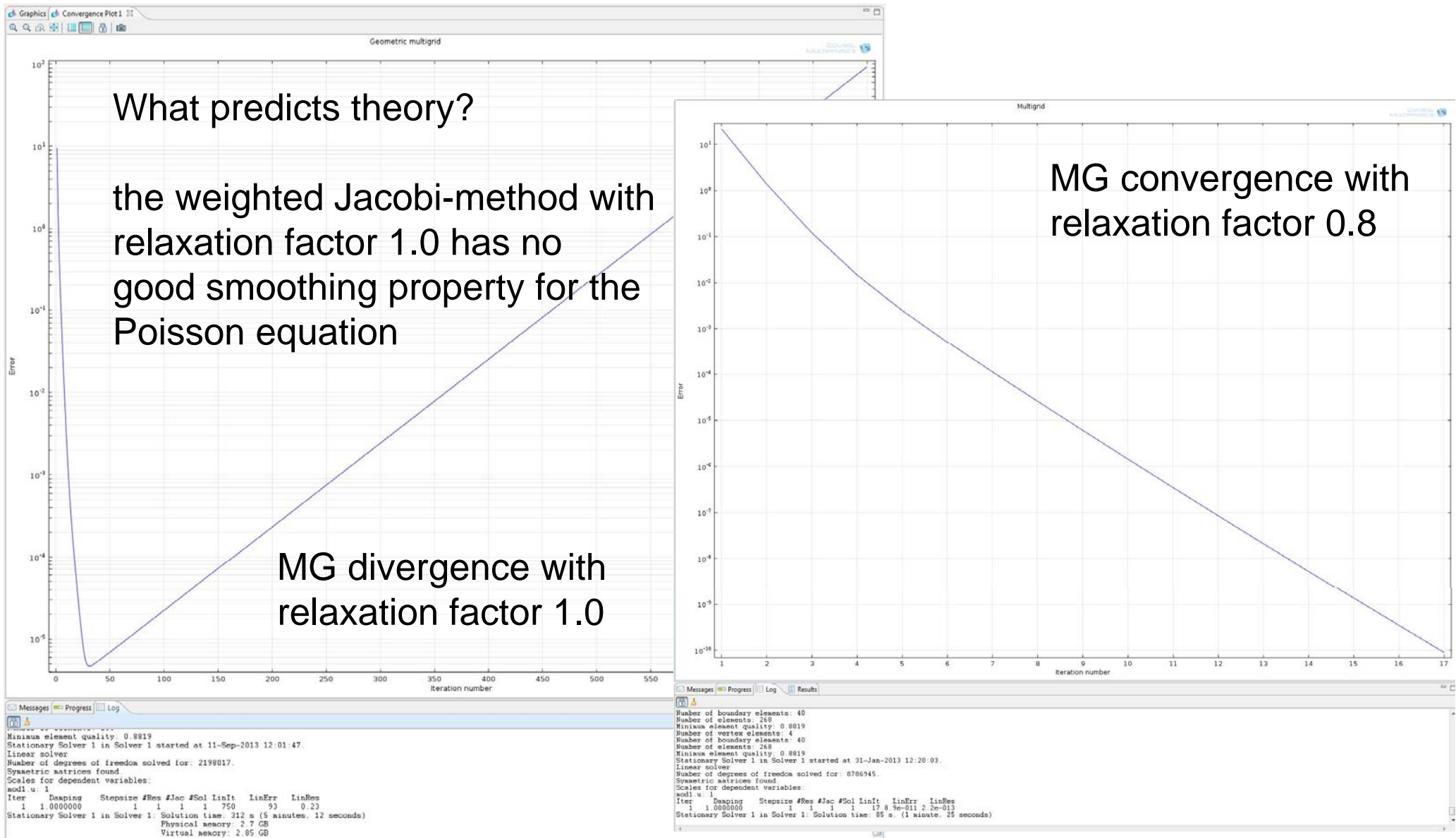
What predicts theory?

the weighted Jacobi-method with relaxation factor 1.0 has no good smoothing property for the Poisson equation, best with 0.8

solver	smoother	total time (seconds)	no. cycles			
MG-W(2,1)-7L	Jacobi $\omega = 1.0$					divergence
MG-V(2,1)-8L	Jacobi $\omega = 1.0$	84	29	1.1		0.402
MG-V(2,1)-8L	Jacobi $\omega = 0.8$	71	17	1.1		0.194
MG-F(2,1)-8L	Jacobi $\omega = 0.8$	77	17	1.4		0.192
MG-W(2,1)-8L	Jacobi $\omega = 0.8$	79	17	1.6		0.192
MG-V(2,1)-9L	Jacobi $\omega = 0.8$	596	17	8.4		0.193
MG-V(2,1)-9L	SOR	450	10	3.0		0.051

the 9L problem could not be solved by a direct solver



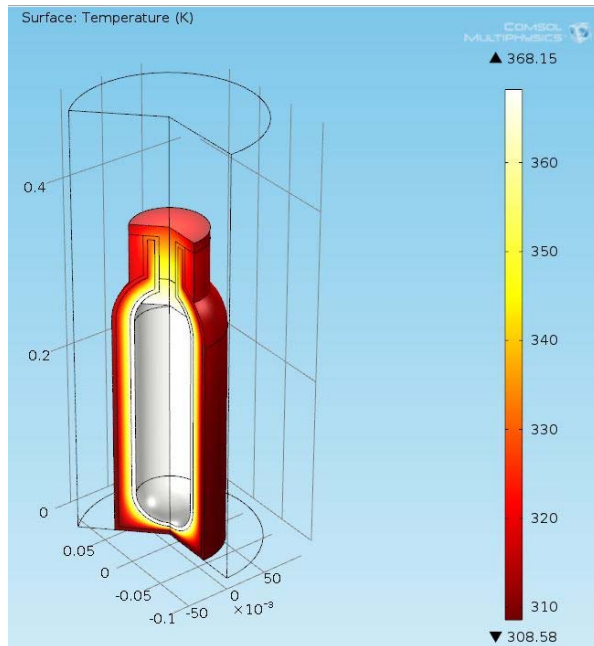


Anisotropic Poisson equation: $\varepsilon_x \frac{\partial^2 u}{\partial x^2} + \varepsilon_y \frac{\partial^2 u}{\partial y^2} = f(x, y)$ with $\varepsilon_x = 0.01, \varepsilon_y = 1.0$
 „free triangular mesh“: **8.786.945 (8L) d.o.f.**

solver	smoother	total time (seconds)	no. of cycles	time per cycle	Q_{comsol}	v. mem. (GB)
MG-V(2,1)-8L	SOR	391	298	1.14	0.915	8.4
MG-F(2,1)-8L	SOR	502	297	1.51	0.915	8.4
MG-W(2,1)-8L	SOR	544	297	1.65	0.915	8.4
MG-V(2,1)-8L	SSOR	407	198	1.79	0.877	8.3
MG-V(2,1)-8L	Vanka	450	198	2.00	0.877	9.7
MG-V(2,1)-8L	SORline	441	68	5.08	0.692	10.3



**cooling of a thermos,
heat transfer, laminar flow,
free convection
stationary, nonlinear**



d.o.f.	solver	total time (seconds)	v. mem. (GByte)
1.975.146	characteristics		
	MG-V(2,1)-6L SOR	50	7.4
	Pardiso	83	11.1
	MUMPS	157	9.9
5.084.465	Spooles	254	8.6
	MG-V(2,1)-7L SOR	128	8.3
	Pardiso	220	19.2
	MUMPS	410	14.8
20.323.281	Spooles	857	20.6
	MG-V(2,1)-8L SOR	695	25.5
	Pardiso	cancelled	-
	MUMPS	cancelled	43.8
	Spooles	omitted	-



What has been observed?

- **numerical complexity of the cycle** is reflected well by the time per cycle
- **convergence speed** of F- and W-cycle are identical
 - F- and W- converge faster than V-cycle
- MG with V(2,1)-cycle usually is the **fastest MG-solver** (time to solve)
- **steady convergence speed** for all cycles (first to last)
- convergence speed is **almost h-independent**
- **linear behavior** is (almost) given
- **moderate memory** requirements, especially when compared to direct solver
- Jacobi smoother reacts on **relaxation parameter** as known from theory
- MG without coloured relaxation pattern or block relaxation behaves as predicted for the **anisotropic Poisson** equation
- **MG beats all direct solver** – except for the anisotropic problem the direct solver could not solve the very large problems

MG implementation in COMSOL is reliable – use it



Literatur

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